

Bayesian analysis of Gaussian

STAT 206

18 Feb 21

sampling models

NB10 case study

Lecture

$$\theta = (\mu, \sigma) \quad (k=2)$$

$$(Y_i | \mu, \sigma \text{ NB}) \stackrel{\text{IID}}{\sim} N(\mu, \sigma^2) \quad (1)$$

$(i=1, \dots, n)$

\downarrow
both unknown

Let's look

at a cut-down version of this model, in which we pretend that σ is known (and equal to the sample SD in the NB10 data set [more cheating, temporarily])

Cut-down Gaussian model ($k=1$)

$$(Y_i | \mu \text{ NB}) \sim p(\mu | \text{NB})$$

$$(Y_i | \mu \text{ NB}) \stackrel{\text{IID}}{\sim} N(\mu, \sigma_0^2)$$

$(i=1, \dots, n)$

\uparrow
known

The likelihood function

$$l(\mu | Y \text{ NB}) = C \exp \left[-\frac{1}{2\sigma_0^2} \sum_{i=1}^n (Y_i - \mu)^2 \right]$$

$$= C \exp \left[-\frac{1}{2\sigma_0^2} \sum_{i=1}^n Y_i^2 + \frac{2\mu}{\sigma_0^2} \sum_{i=1}^n Y_i - \frac{n\mu^2}{2\sigma_0^2} \right]$$

Conjugate prior?

After simplification, ^(ugly algebra) something really nice pops out: (2)

lecture notes part 6 p. 126 +

$$L(\mu | \mathcal{N}, \mathcal{B}) = C \exp \left[-\frac{1}{2 \left(\frac{\sigma_0^2}{n}\right)} (\mu - \bar{y})^2 \right]$$

$$= N(\bar{y}, \frac{\sigma_0^2}{n}) \text{ as a PDF in } \mu (!)$$

Q1: Is this a familiar family of PDFs? **A1** yes

Q2: Is the product of 2 Gaussian PDFs another one? **A2** ^(ugly algebra) Turns out to be

for n IID yes.
So the conjugate prior in the $N(\mu, \sigma_0^2)$ sampling model is also Normal:

$$(\mu | \mathcal{N}, \mathcal{B}) \sim N(\mu_0, \sigma_\mu^2)$$
$$(\mathcal{Y}_i | \mu, \mathcal{N}_s, \mathcal{B}) \stackrel{\text{IID}}{\sim} N(\mu, \sigma_0^2)$$

($i = 1, \dots, n$)

N_s = Normal sampling dist.
 N_μ = Normal prior
known

The conjugate updating rule here is $\textcircled{3}$
 genuinely beautiful:
 (only algebra)
 \bar{y} is a minimal suff. stat for μ

$$\left\{ \begin{array}{l} (\mu | N, \beta) \sim N(\mu_0, \sigma_\mu^2) \\ (Z_i | \mu, N_i, \beta) \stackrel{IID}{\sim} N(\mu, \sigma_0^2) \\ (i=1, \dots, n) \end{array} \right. \quad \left. \begin{array}{l} \bar{y} = (y_1, \dots, y_n) \\ \rightarrow \end{array} \right.$$

(known)

$(\mu | \bar{y}, N_s, N_p, \beta) \sim N(\mu_*, \sigma_*^2)$ with

$$\mu_* = \frac{\frac{1}{\sigma_\mu^2} (\mu_0) + \frac{n}{\sigma_0^2} (\bar{y})}{\left(\frac{1}{\sigma_\mu^2}\right) + \left(\frac{n}{\sigma_0^2}\right)} = \frac{\left(\frac{\sigma_0^2}{\sigma_\mu^2}\right) (\mu_0) + (n) (\bar{y})}{\left(\frac{\sigma_0^2}{\sigma_\mu^2}\right) + n}$$

prior sample size n_0

$$\frac{\left(\frac{1}{\sigma_\mu^2}\right) + \left(\frac{n}{\sigma_0^2}\right)}{\left(\frac{\sigma_0^2}{\sigma_\mu^2}\right) + n}$$

and $\sigma_*^2 = \frac{1}{\left(\frac{1}{\sigma_\mu^2}\right) + \left(\frac{n}{\sigma_0^2}\right)} = \frac{\sigma_0^2}{\left(\frac{\sigma_0^2}{\sigma_\mu^2}\right) + n}$

data sample size

prior sample size (n_0)

$$\left(\begin{array}{l} \text{prior} \\ \text{variance} \\ \text{for } \mu \end{array} \right) = \underline{\underline{\sigma^2}} \quad \left(\begin{array}{l} \text{likelihood} \\ \text{variance} \\ \text{for } \mu \end{array} \right) = \underline{\underline{\frac{\sigma^2}{n}}} \quad (4)$$

Notice that these quantities enter into μ^* as reciprocals: $\left(\frac{1}{\sigma^2} \right)$ and $\left(\frac{n}{\sigma^2} \right)$
 are the weights in the weighted average
 representative of the posterior mean:

Bayesian
 definition

\mathcal{I} any random variable with
variance $\sigma^2 > 0 \rightarrow$ the
precision of \mathcal{I} is just

the reciprocal $\left(\frac{1}{\sigma^2} = \text{precision} = \tau \right)$
 of the variance ↑
"tau"

(8)

$$\begin{aligned}
 \left(\begin{array}{l} \text{posterior} \\ \text{mean} \\ \text{for } \mu \end{array} \right) &= \mu_* = \left(\begin{array}{l} \text{prior} \\ \text{precision} \end{array} \right) \left(\begin{array}{l} \text{prior} \\ \text{mean} \end{array} \right) + \\
 &= \left(\begin{array}{l} \text{likelihood} \\ \text{precision} \end{array} \right) \cdot \left(\begin{array}{l} \text{data} \\ \text{mean} \end{array} \right) \\
 &= \frac{\left(\frac{1}{\sigma_\mu^2} \right) \mu_0 + \left(\frac{h}{\sigma_0^2} \right) \bar{y}}{\left(\frac{1}{\sigma_\mu^2} \right) + \frac{h}{\sigma_0^2}} \cdot \frac{\left(\begin{array}{l} \text{prior} \\ \text{precision} \end{array} \right) + \left(\begin{array}{l} \text{likelihood} \\ \text{precision} \end{array} \right)}
 \end{aligned}$$

$$\begin{aligned}
 \left(\begin{array}{l} \text{posterior} \\ \text{precision} \\ \text{for } \mu \end{array} \right) &= \frac{1}{\sigma_*^2} = \left(\frac{1}{\sigma_\mu^2} \right) + \left(\frac{h}{\sigma_0^2} \right) \\
 &= \left(\begin{array}{l} \text{prior} \\ \text{precision} \end{array} \right) + \left(\begin{array}{l} \text{likelihood} \\ \text{precision} \end{array} \right)
 \end{aligned}$$

on this scale, information is additive

$$\left\{ \begin{array}{l} (\mu, \sigma | \mathcal{B}) \sim p(\mu, \sigma | \mathcal{B}) \\ (\bar{Z}_i | \mu, \sigma, N, \mathcal{B}) \stackrel{i.i.d.}{\sim} N(\mu, \sigma^2) \\ (i=1, \dots, n) \end{array} \right\} \quad \text{⑥}^{\circ}$$

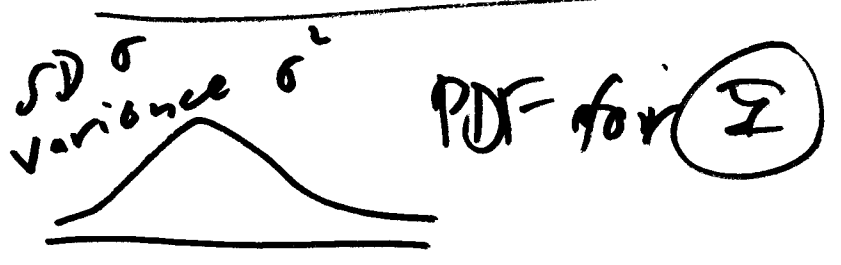
$\theta = (\mu, \sigma)$
or $\theta = (\mu, \sigma^2)$
 $\theta_1 \sim \theta_k$

(k=2)

$$p(\underline{\theta} | \bar{Z} \sim N(\cdot, \cdot) | \mathcal{B}) = c \frac{p(\underline{\theta} | \mathcal{B})}{Q(\underline{\theta} | \bar{Z} \sim N(\cdot, \cdot) | \mathcal{B})}$$

(R² → R) (R² → R) · $\frac{R^2 \rightarrow R}{R^2 \rightarrow R}$

this will work for any finite $k \geq 1$



$$V(\bar{Z}) = \sigma^2 > 0$$

$$SD(\bar{Z}) = \sigma > 0$$

{ SD variance of \bar{Z} } ↔ (what we don't know about \bar{Z}) ↔ uncertainty

(reciprocal of variance) ↔ (what we do know about \bar{Z}) ↔ information

(general $k \geq 2$) $\theta = (\theta_1, \dots, \theta_k)$

$p(\theta_2 | D(\dots) \mathcal{B}) =$

$p(\theta_2 | (\dots) \mathcal{B})$
 $p(\theta_2 | \mathcal{D}(\dots) \mathcal{B})$

normalizing constant

$$c^{-1} = \int \dots \int p(\theta_2 | (\dots) \mathcal{B}) \cdot p(\theta_2 | \mathcal{D}(\dots) \mathcal{B}) d\theta_1 d\theta_2 \dots d\theta_k$$

$\leftarrow k \rightarrow$

marginals k of them, each requiring a $(k-1)$ -dimensional integral:

ex. $p(\theta_2 | D(\dots) \mathcal{B}) = \int \int \int \dots \int$ posterior

$\theta_1 \theta_3 \dots \theta_k$

predictive list.

$D = (y_1, \dots, y_n) = \mathcal{Y}$

$p(y_{n+1} | \mathcal{Y}(\dots) \mathcal{B}) =$

another k -dimensional integral

new (future) data

$$(\mu, \sigma^2 | \textcircled{?} \mathcal{B}) \sim p(\mu, \sigma^2 | \textcircled{?} \mathcal{B})$$

$$(I_i | \mu, \sigma^2 | \mathcal{B}) \stackrel{IID}{\sim} \mathcal{N}(\mu, \sigma^2)$$

Conj. prior $\textcircled{8}$

(i = 1, \dots, n)

(N - I_G prior exists)

$$p(\mu, \sigma^2 | \textcircled{?} \mathcal{B}) = p(\mu | \textcircled{?} \mathcal{B}) \cdot p(\sigma^2 | \mu, \textcircled{?} \mathcal{B})$$

$$= \boxed{p(\sigma^2 | \textcircled{?} \mathcal{B}) / p(\mu | \sigma^2, \textcircled{?} \mathcal{B})}$$

do not meet but that's useful

intuitive

hierarchical prior $\left. \begin{matrix} \textcircled{1} (\sigma^2 | \textcircled{?} \mathcal{B}) \\ \downarrow \\ \textcircled{2} (\mu | \sigma^2, \textcircled{?} \mathcal{B}) \end{matrix} \right\} =$

(2 levels or layers to the hierarchy)

$$p(\mu, \sigma^2 | \textcircled{?} \mathcal{B})$$

(SI - χ^2)

$$(\sigma^2 | \textcircled{?} \mathcal{B}) \sim \chi^{-2}(\nu_0, \sigma_0^2)$$

χ^2 dist: see Gelman et al. App. A

prior sample size for σ^2 prior estimate of σ^2

$$(\mu, \sigma^2 | \text{CP } \mathcal{B}) \sim \text{CP}(\mu, \sigma^2 | \mathcal{B})$$

$$(z_i | \mu, \sigma^2, N_s, \mathcal{B}) \stackrel{\text{IID}}{\sim} N(\mu, \sigma^2)$$

$(i = 1, \dots, n)$

LI
conj.

prior:

$\gamma_0 = 0$ ← prior sample size for σ^2

$k_0 = 0$ → prior sample size for μ

$$(\mu | z, N_s, \text{CP } \mathcal{B}) \sim$$

$$t_n(\mu_n, \frac{\sigma_n^2}{k_n})$$

$$\mu_n = \bar{y}$$

$$\sigma_n^2 = \frac{n-1}{n} s^2$$

$$\gamma_n = \gamma_0 + n \rightarrow n$$

$$k_n = k_0 + n \rightarrow n$$

$$\hat{\mu}_{MLE} = \bar{y} \quad t_{100}(\bar{y}, \frac{s^2}{n})$$

$$\downarrow \Leftrightarrow (\mu | \sim) \stackrel{\text{approx}}{\sim} N(\bar{y}, \frac{s^2}{n})$$

$$SE^2(\hat{\mu}_{MLE}) = \frac{s^2}{n} \checkmark$$